

# Advanced Learning Models

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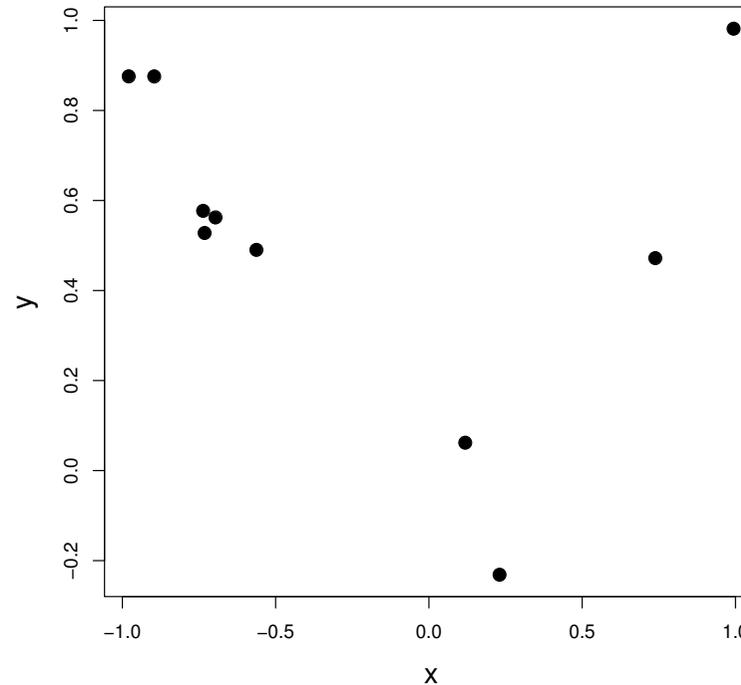
# Part I

Overfitting, bias-variance tradeoff: what is the problem?

Thanks to Laurent Jacob for sharing slides!

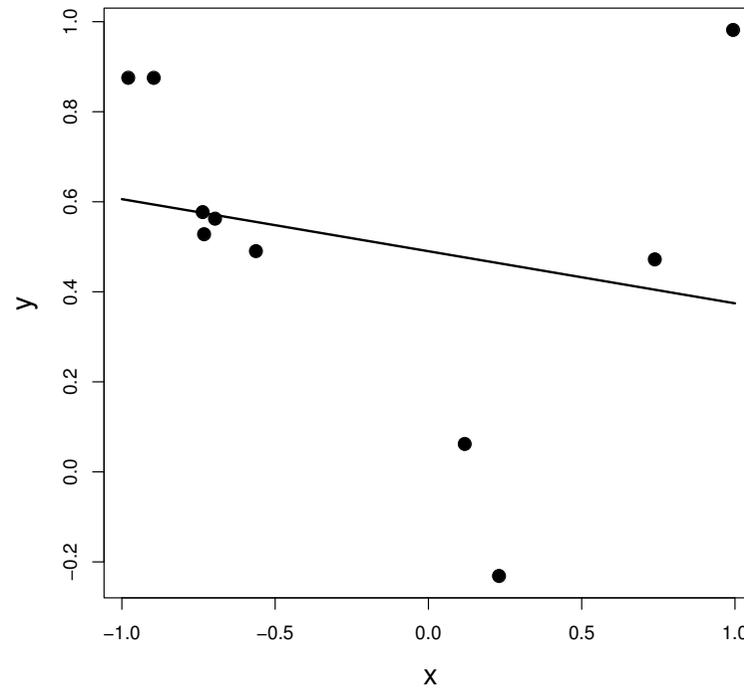
- We start with an informal example.
- We will formalize what we observe later.

# Bias-variance tradeoff: intuition



- We observe 10 couples  $(x_i, y_i)$ .
- We want to estimate  $y$  from  $x$ .
- **Our first strategy:** find  $f$  such that  $f(x_i)$  is close to  $y_i$ .

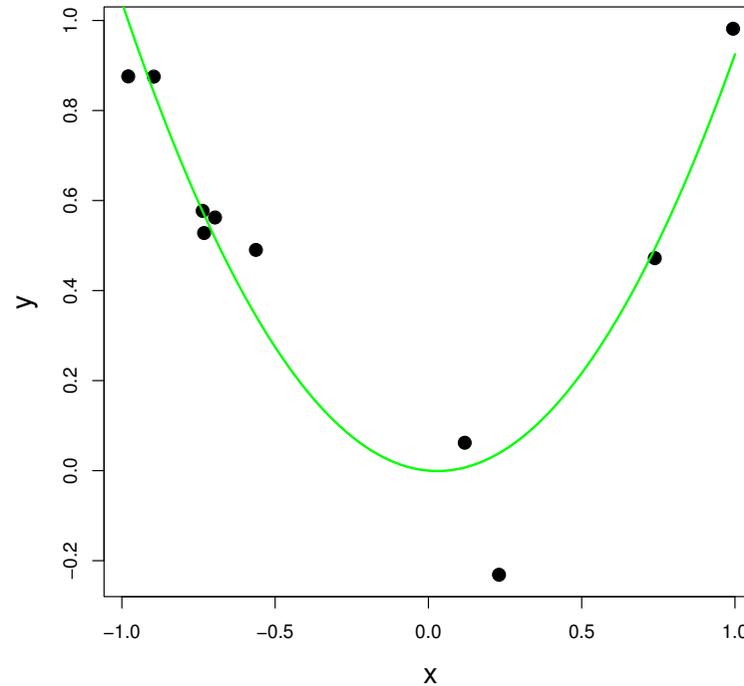
# Bias-variance tradeoff: intuition



Find  $f$  as a line

$$\min_{f(x)=ax+b} \|Y - f(X)\|^2$$

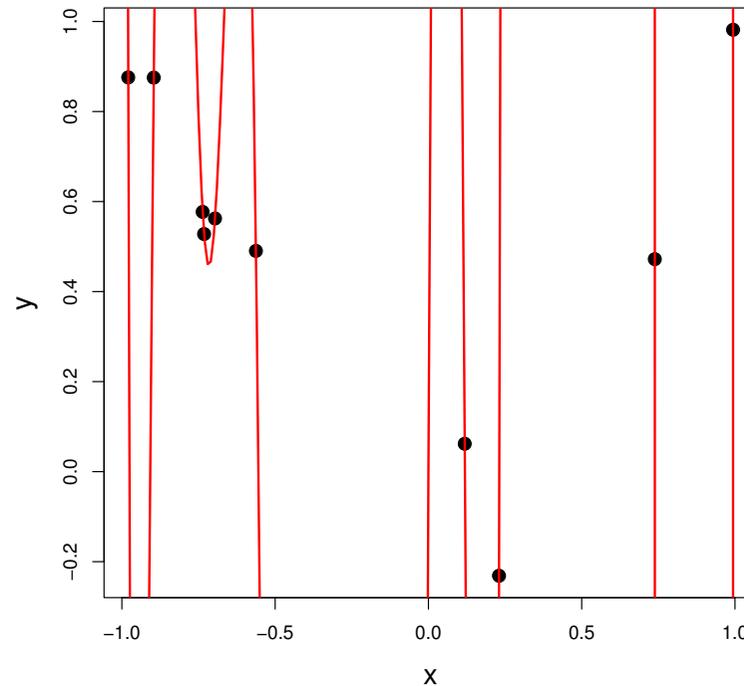
# Bias-variance tradeoff: intuition



Find  $f$  as a quadratic function

$$\min_{f(x)=ax^2+bx+c} \|Y - f(X)\|^2$$

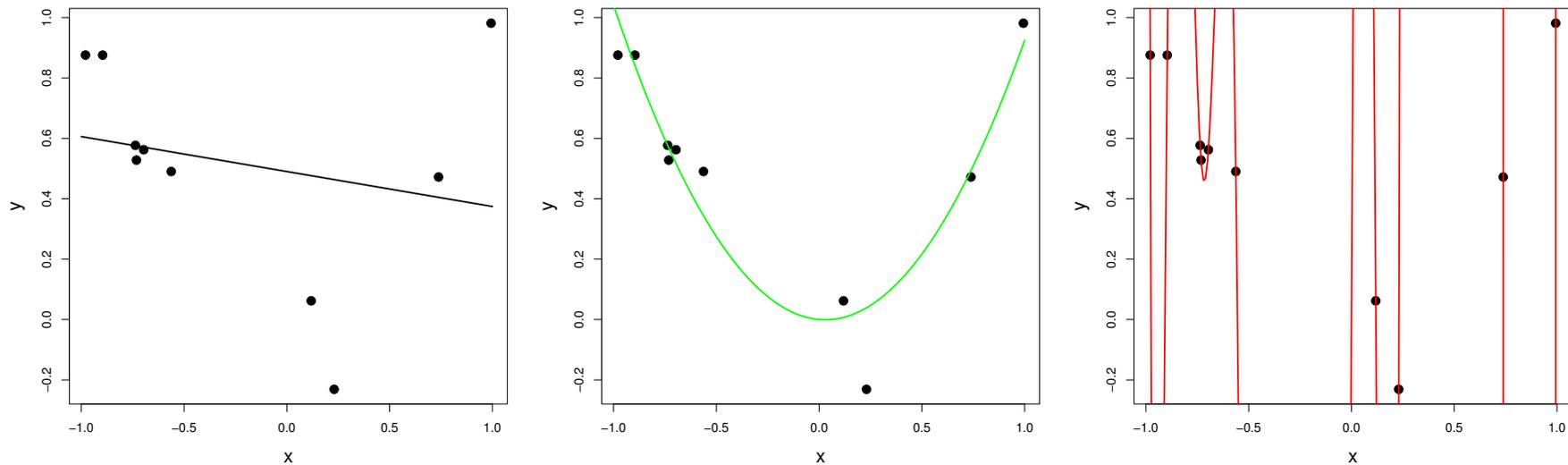
# Bias-variance tradeoff: intuition



Find  $f$  as a polynomial of degree 10

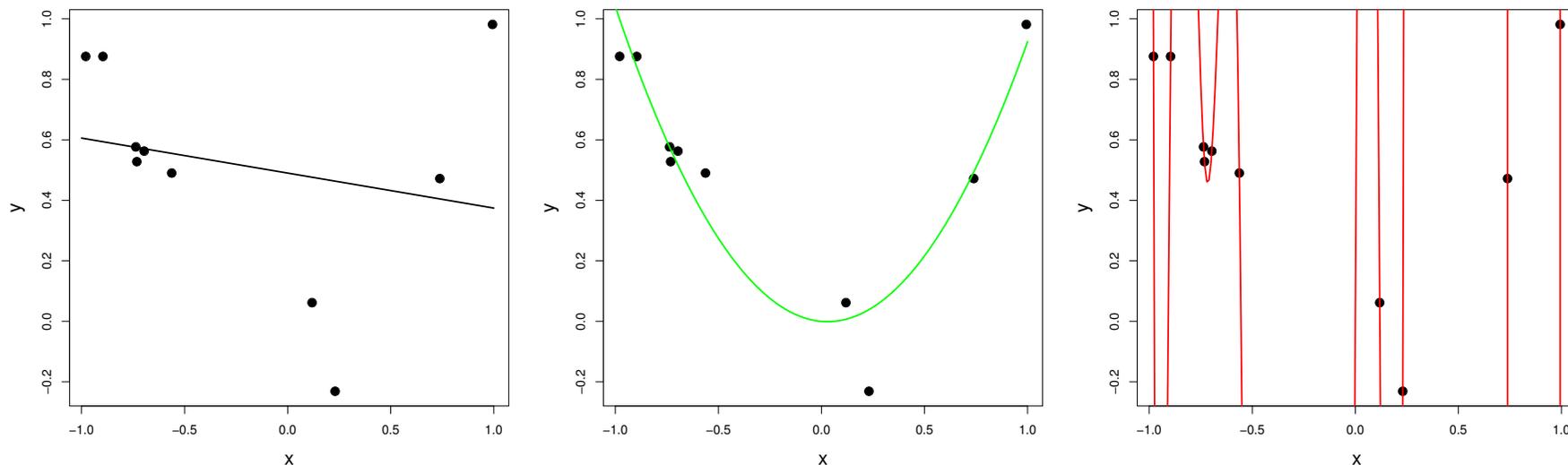
$$f(x) = \sum_{j=0}^{10} a_j x^j \quad \min_{a_j} \|Y - f(X)\|^2$$

# Bias-variance tradeoff: intuition



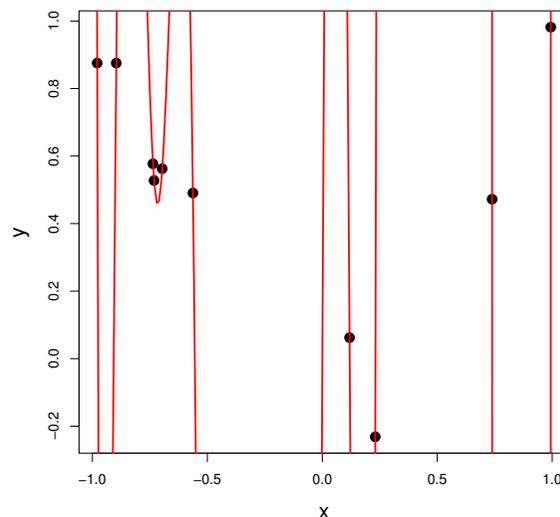
Which function would you trust to predict  $y$  corresponding to  $x = 0.5$ ?

# Bias-variance tradeoff: intuition



- Reminder: we aim at “finding  $f$  such that  $f(x_i)$  is close to  $y_i$ ”.
- With the polynomial of degree 10,  $f(x_i) - y_i = 0$  for all 10 points.
- There is something wrong with our objective.

# Bias-variance tradeoff: intuition

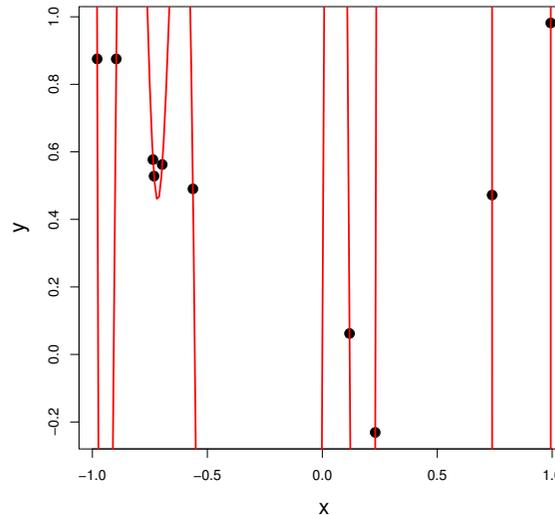


More precisely:

- If we allow **any** function  $f$ , we can find a **lot** of perfect solutions for the training data.
- Our actual goal is to estimate  $y$  for **new points**  $x$  from the same population :

$$\min_f \mathbb{E}_{(X,Y)} \|Y - f(X)\|^2$$

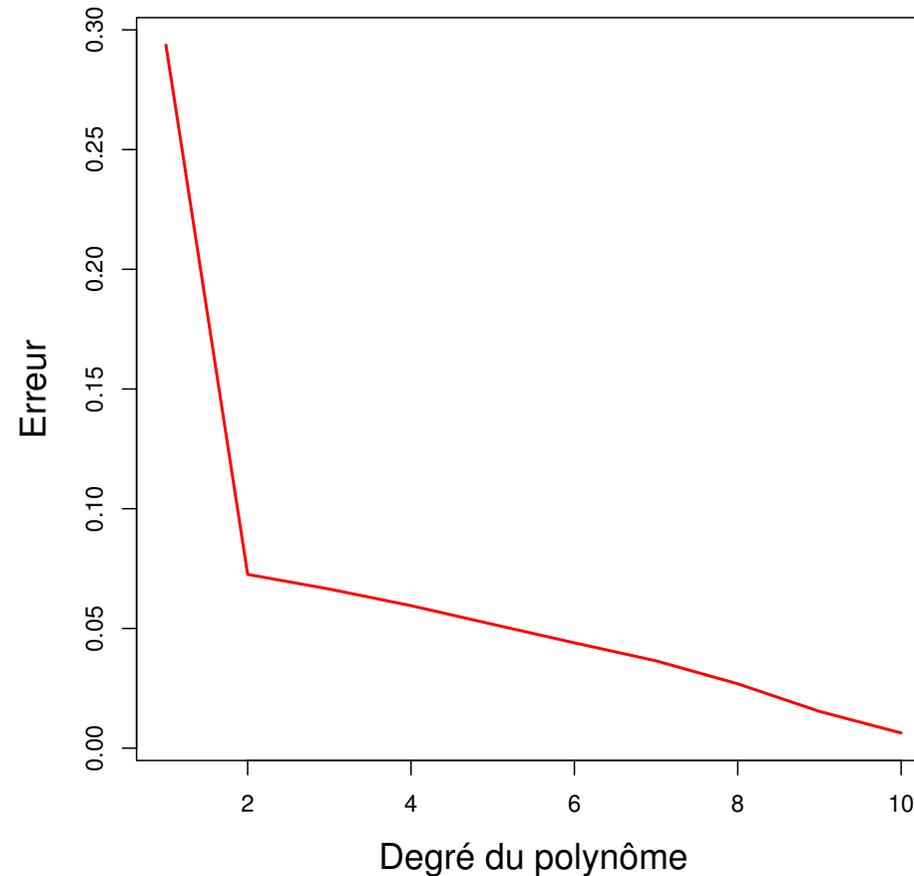
# Biais-variance tradeoff: intuition



Even more precisely :

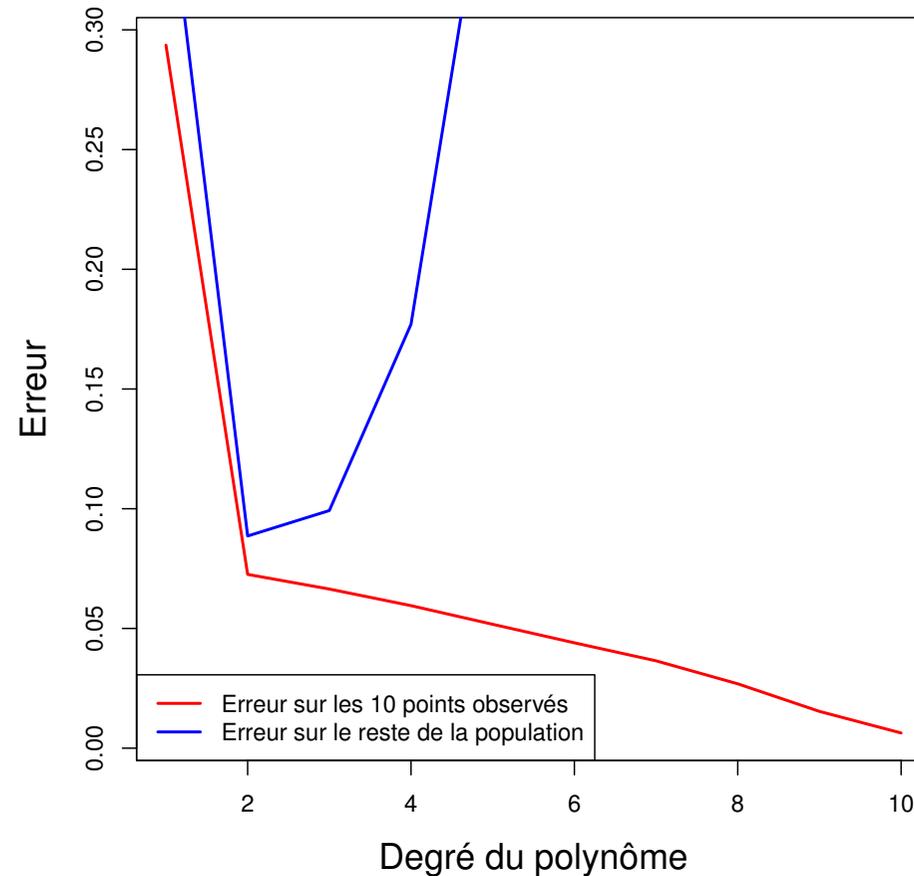
- We did not take into account the fact that our 10 points are a subsample from the population.
- If we sample 10 new points from the same population, the complex functions are likely to change more than the simple ones.
- Consequence: these functions will probably generalize less well to the rest of the population.

# Overfitting



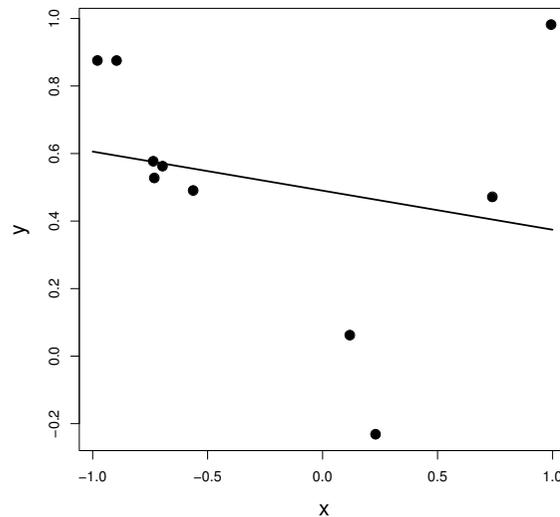
- When the degree increases, the error  $\|y - f(x)\|^2$  over the 10 observations always decreases.
- Over the rest of the population, the error decreases, then increases.

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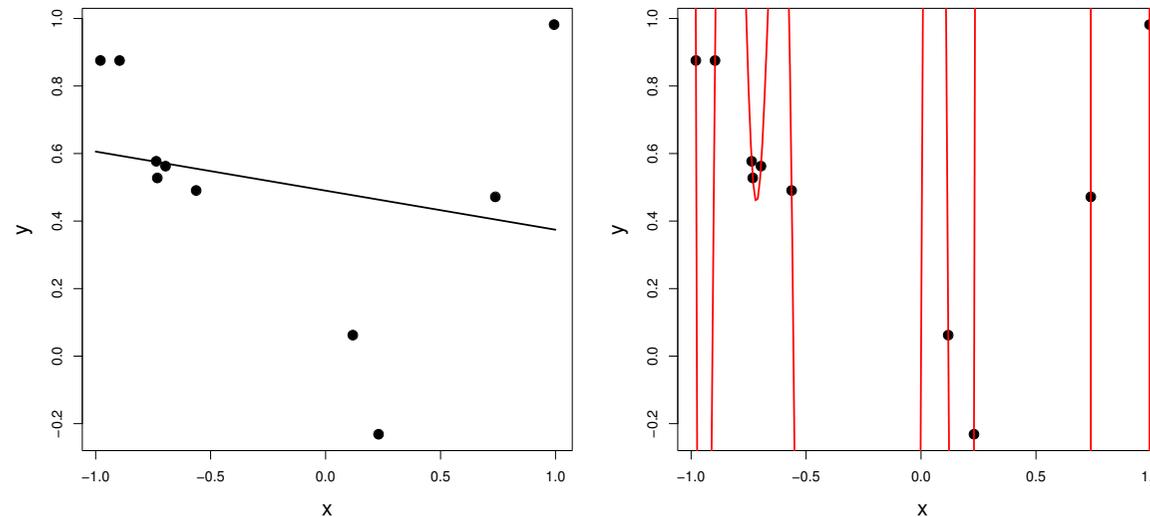
# Overfitting



This suggests the existence of a **tradeoff** between two types of errors:

- Sets of functions which are too simple cannot contain functions which explain the data well enough.
- Sets of functions which are too rich may contain functions which are too specific to the observed sample.

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# Parenthesis: complexity vs dimension (1/3)

- Our introductory examples had a **large number of descriptors**.
- This case involves increasingly **complex** functions of a single variable.

# Parenthesis : complexity vs dimension (2/3)

- In fact, the two notions are related: here in particular, the three functions are linear in different representations.
- Reminder (linear regression):  
$$\arg \min_{\theta \in \mathbb{R}^p} \|Y - X\theta\|^2 = (X^\top X)^{-1} X^\top Y \text{ (if } X^\top X \text{ is invertible).}$$
- How can we use this fact to compute  
$$\arg \min_{f(x) = \sum_{j=1}^p a_j x^j} \|Y - f(X)\|^2?$$

# Parenthesis : complexity vs dimension (3/3)

- We could have illustrated the same principle using linear functions involving more and more variables.
- Example : predicting a phenotype using the expression of an increasing number of genes.
- We stuck to polynomials, which allow for better visual representations.
- Along this class, the notion of complexity of a set of functions will become more and more precise.
- Complexity is what causes problems for inference, not just dimension.

## Second parenthesis : models

- Until now, we did not need to introduce a **model** for the data, *i.e.*, a distribution over  $\mathcal{X} \times \mathcal{Y}$  :
  - Data could come from any population.
  - The functions we used to predict  $y$  can be derived from particular probabilistic models, but this is not necessary (they were in fact historically introduced without a model).
- The objective is not to criticize the use of models, but to show that the tradeoff problem we introduced goes beyond probabilistic models.
- We now show how using a model can give a better insight into the problem.

# A little more formally: bias-variance decomposition

- We now assume that the data follow:

$$y = f(x) + \varepsilon, \quad (1)$$

and  $\mathbf{E}[\varepsilon] = 0$ .

- Without loss of generality, we consider an estimator  $\hat{f}$  of  $f$ , which is a function of training data  $\mathcal{D} = (x_i, y_i)_{(i=1, \dots, n)}$  sampled i.i.d. from (1)
- Note:  $\hat{f}$  is a random function.
- We consider the mean **quadratic error**  $\mathbf{E}[(y - \hat{f}(x))^2]$  incurred when using  $\hat{f}$  to estimate for a given  $x$  the corresponding  $y$  sampled from (1) independently from  $\mathcal{D}$ .
- Expectation is taken over  $\mathcal{D}$  used to estimate  $\hat{f}$ , and  $\varepsilon = y - f(x)$ .

# A little more formally: biais-variance decomposition

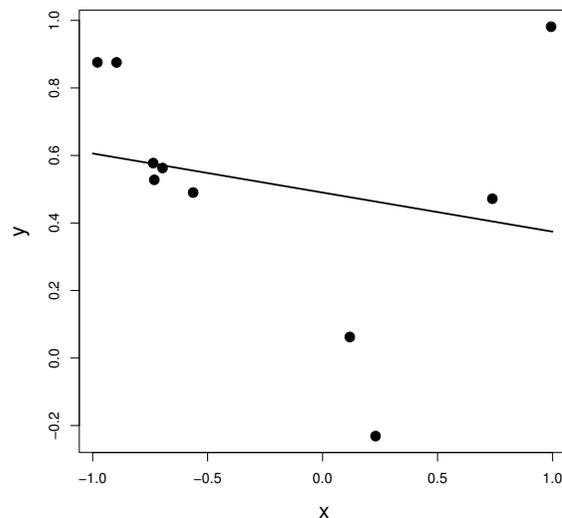
## Proposition

*Under the previous hypotheses,*

$$\mathbf{E}[(y - \hat{f}(x))^2] = \left( \mathbf{E}[\hat{f}(x)] - f(x) \right)^2 + \mathbf{E} \left[ \left( \mathbf{E}[\hat{f}(x)] - \hat{f}(x) \right)^2 \right] + \mathbf{E}[(y - f(x))^2]$$

- The first term is the squared **bias** of  $\hat{f}$ : the difference between its mean (over the sample of  $\mathcal{D}$ ) and the true  $f$ .
- The second term is the **variance** of  $\hat{f}$ : how much  $\hat{f}$  varies around its average when the dataset  $\mathcal{D}$  changes.
- The third term is the Bayes error, and does not depend on the estimator. The actual quantity of interest is the **excess of risk**  $\mathbf{E}[(y - \hat{f}(x))^2] - \mathbf{E}[(y - f(x))^2]$ .

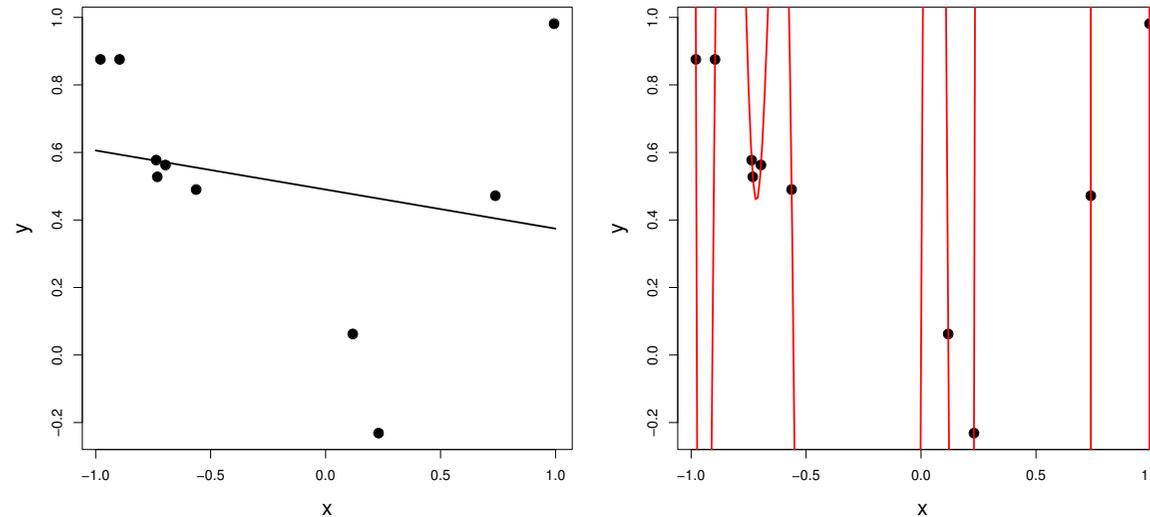
# Back to our example



## Tradeoff between two types of error:

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these sets lead to estimators with a large **bias**.
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## Reminder (König-Huygens)

For any real random variable  $Z$ ,  $\mathbf{E} \left[ (Z - \mathbf{E}[Z])^2 \right] = \mathbf{E}[Z^2] - \mathbf{E}[Z]^2$

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# Biais-variance decomposition: proof

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# Biais-variance decomposition : perspective

$$\mathbf{E}[(y - \hat{f}(x))^2] = \left( \mathbf{E}[\hat{f}(x)] - f(x) \right)^2 + \mathbf{E} \left[ \left( \mathbf{E}[\hat{f}(x)] - \hat{f}(x) \right)^2 \right] + \mathbf{E}[(y - f(x))^2]$$

- Using a (rather general) model, we managed to start formalizing the tradeoff introduced with our example.
- Decomposition valid for any  $x$ , thus also in expectation over independent  $x$ .