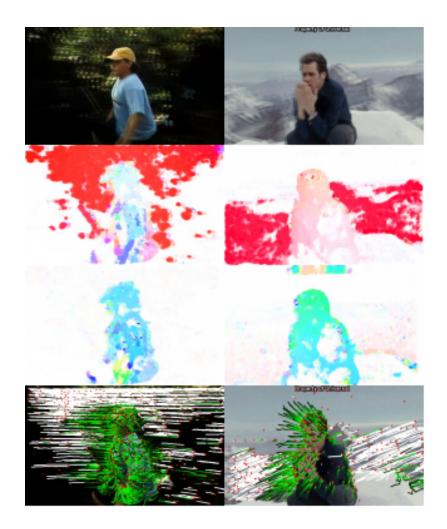
## Action Recognition with Improved Trajectories

## Introduction

- Current approach based on space-time features, dense trajectory
- Suggested method aim to remove the motion of the camera for a more accurate trajectory

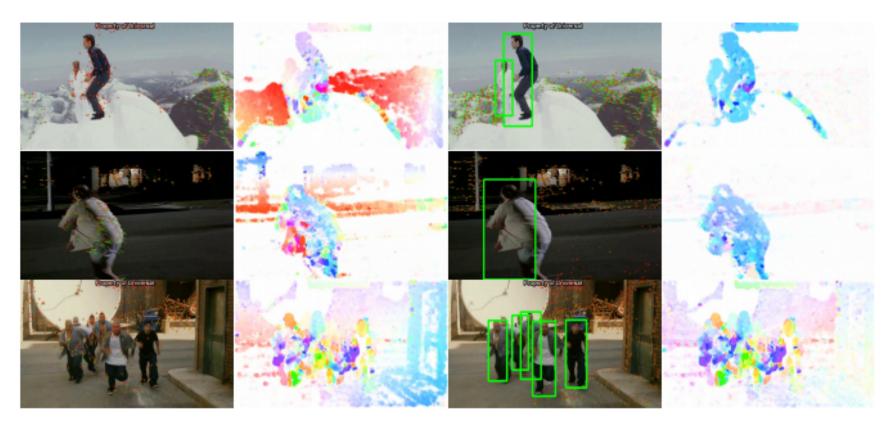


## Camera Motion Estimation

- Extract SURF features
- Estimate Homography => Camera Motion
- Rectified optical flow
- Threshold the trajectories



#### Human-Background Inconsistent Matches



# **Trajectory Features**

- ->Feature points (15 frames)
- ->descriptors :
  - estimate homography
- warp next frame with previous homography
- compute descriptor (trajectory, HOF, MBH) based on warped flow
- normalized histogram

#### Results



(a) AnswerPhone

(a) GetOutCar

(b) Push-Up

(b) Chew







(c) Vault

(c) Tennis-Serve

(d) Punch

(d) Ski-Jet

### Results

|                   | Hollywood2              |                                     |                                    |                         | HMDB51                  |                                     |                                    |                         |
|-------------------|-------------------------|-------------------------------------|------------------------------------|-------------------------|-------------------------|-------------------------------------|------------------------------------|-------------------------|
|                   | Baseline                | WarpFlow                            | RmTrack                            | Combined                | Baseline                | WarpFlow                            | RmTrack                            | Combined                |
| Trajectory        | 42.2%                   | 47.6%                               | 42.4%                              | 48.5%                   | 25.4%                   | 31.0%                               | 26.9%                              | 32.4%                   |
| HOG               | 46.9%                   | 46.2%                               | 46.7%                              | 47.1%                   | 38.4%                   | 38.7%                               | 39.6%                              | 40.2%                   |
| HOF               | 51.4%                   | 58.1%                               | 53.4%                              | 58.8%                   | 39.5%                   | 48.5%                               | 41.6%                              | 48.9%                   |
| MBH               | 57.4%                   | 60.3%                               | 58.6%                              | 60.5%                   | 49.1%                   | 50.9%                               | 50.8%                              | 52.1%                   |
| HOF+MBH           | 58.2%                   | 62.3%                               | 59.7%                              | 62.6%                   | 49.8%                   | 53.5%                               | 51.0%                              | 54.7%                   |
| Combined          | 60.1%                   | 63.6%                               | 61.7%                              | 64.3%                   | 52.2%                   | 55.6%                               | 53.9%                              | 57.2%                   |
|                   |                         |                                     |                                    |                         |                         |                                     |                                    |                         |
|                   |                         | Olympi                              | c Sports                           |                         |                         | UC                                  | F50                                |                         |
|                   | Baseline                | Olympi<br>WarpFlow                  | c Sports<br>RmTrack                | Combined                | Baseline                | UC<br>WarpFlow                      | F50<br>RmTrack                     | Combined                |
| Trajectory        | Baseline<br>62.4%       |                                     |                                    | Combined<br>77.2%       | Baseline<br>65.3%       |                                     |                                    | Combined<br>75.2%       |
| Trajectory<br>HOG |                         | WarpFlow                            | RmTrack                            |                         |                         | WarpFlow                            | RmTrack                            |                         |
|                   | 62.4%                   | WarpFlow<br>73.7%                   | RmTrack<br>66.3%                   | 77.2%                   | 65.3%                   | WarpFlow<br>72.6%                   | RmTrack<br>67.8%                   | 75.2%                   |
| HOG               | 62.4%<br>77.0%          | WarpFlow<br>73.7%<br>76.3%          | RmTrack<br>66.3%<br>78.7%          | 77.2%<br>78.8%          | 65.3%<br>81.8%          | WarpFlow<br>72.6%<br>81.6%          | RmTrack<br>67.8%<br>82.6%          | 75.2%<br>82.6%          |
| HOG<br>HOF        | 62.4%<br>77.0%<br>74.5% | WarpFlow<br>73.7%<br>76.3%<br>86.2% | RmTrack<br>66.3%<br>78.7%<br>77.6% | 77.2%<br>78.8%<br>87.6% | 65.3%<br>81.8%<br>74.3% | WarpFlow<br>72.6%<br>81.6%<br>85.4% | RmTrack<br>67.8%<br>82.6%<br>79.4% | 75.2%<br>82.6%<br>85.1% |